

# Data Structures and Algorithms

## (CS210A)

### Lecture 12:

- **Queue** : a new data Structure :
- Finding **shortest route in a grid** in presence of obstacles

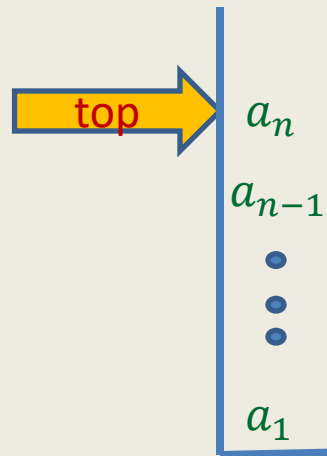
# Queue: a new data structure

## Data Structure Queue:

- Mathematical Modeling of Queue
- Implementation of Queue using arrays

# Stack

A special kind of list where all operations (insertion, deletion, query) take place at one end only, called the **top**.



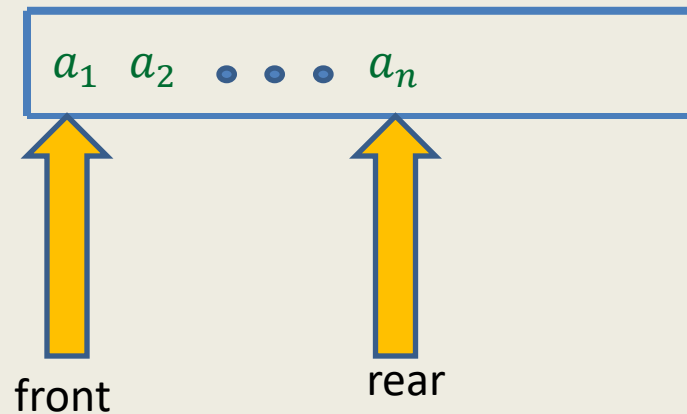
Behavior of Stack: (LIFO)

Last in First out

# Queue: a new data structure

A special kind of list based on (FIFO)

**First in First Out**



# Operations on a Queue

## Query Operations

- **IsEmpty(Q)**: determine if **Q** is an empty queue.
- **Front(Q)**: returns the element at the **front** position of the queue.

**Example:** If **Q** is  $a_1, a_2, \dots, a_n$ , then **Front(Q)** returns  $a_1$ .

## Update Operations

- **CreateEmptyQueue(Q)**: Create an empty queue
- **Enqueue(x,Q)**: insert **x** at the **end** of the queue **Q**

**Example:** If **Q** is  $a_1, a_2, \dots, a_n$ , then after **Enqueue(x,Q)**, queue **Q** becomes

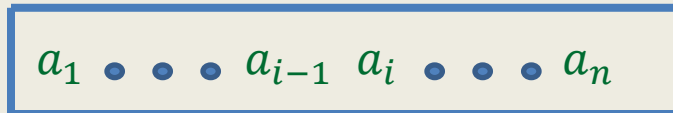
$a_1, a_2, \dots, a_n, x$

- **Dequeue(Q)**: return element from the **front** of the queue **Q** and delete it

**Example:** If **Q** is  $a_1, a_2, \dots, a_n$ , then after **Dequeue(Q)**, queue **Q** becomes

$a_2, \dots, a_n$

# How to access $i$ th element from the front ?



- To access  $i$ th element, we **must** perform **dequeue** (hence delete) the first  $i - 1$  elements from the queue.

**An Important point you must remember for every data structure**

You can define any **new** operation only in terms of the primitive operations of the data structures defined during its modeling.

# Implementation of Queue using array

**Assumption:** At any moment of time, the number of elements in queue is  $n$ .

Keep an array of  $Q$  size  $n$ , and two variables  $front$  and  $rear$ .

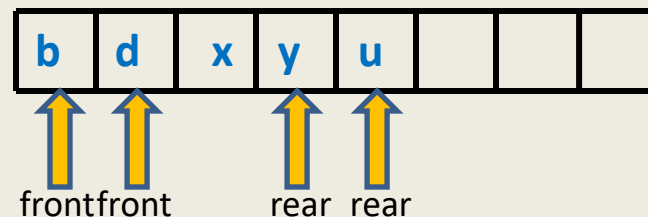
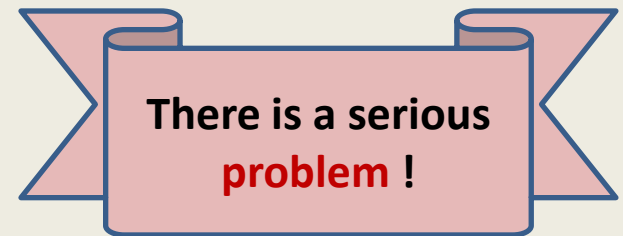
- $front$ : the position of the **first** element of the queue in the array.
- $rear$ : the position of the **last** element of the queue in the array.

**Enqueue**( $x, Q$ )

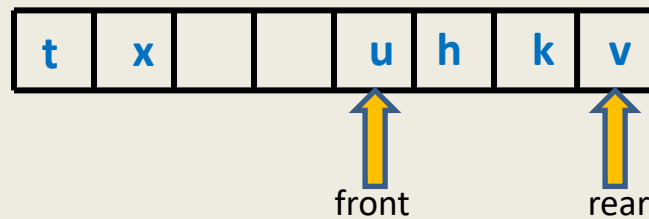
```
{   rear  $\leftarrow$  rear+1;  
    Q[rear]  $\leftarrow$  x  
}
```

**Dequeue**( $Q$ )

```
{   x  $\leftarrow$  Q[front];  
    front  $\leftarrow$  front+1;  
    return x;}
```



# Implementation of Queue using array



How to perform  
**Enqueue**(**x**,**Q**) ?



# Implementation of Queue using array

**Enqueue**(x,Q)

```
{   rear ← (rear+1) mod n ;  
    Q[rear] ← x  
}
```

**Dequeue**(Q)

```
{   x ← Q[front];  
    front ← (front+1) mod n ;  
    return x;  
}
```

**IsEmpty**(Q)

```
{   Do it as an exercise   }
```

# Shortest route in a grid with obstacles

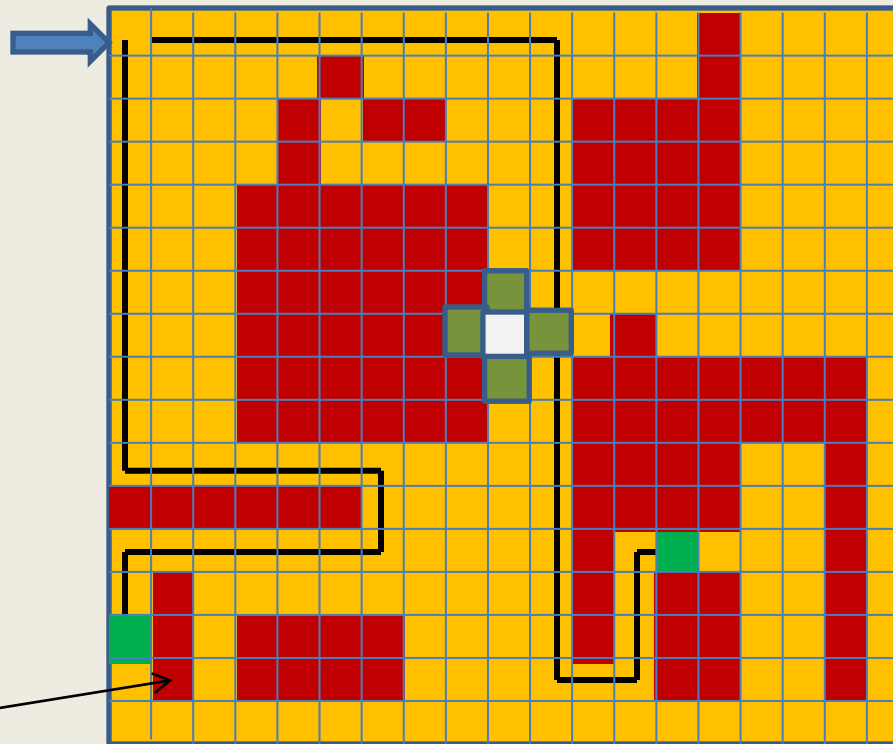
# Shortest route in a grid

From a cell in the grid, we can move to any of its neighboring cell in one step.

**Problem:** From top left corner, find shortest route to each cell avoiding obstacles.

**Input** : a Boolean matrix  $G$  representing the grid such that

$G[i, j] = 0$  if  $(i, j)$  is an obstacle, and 1 otherwise.

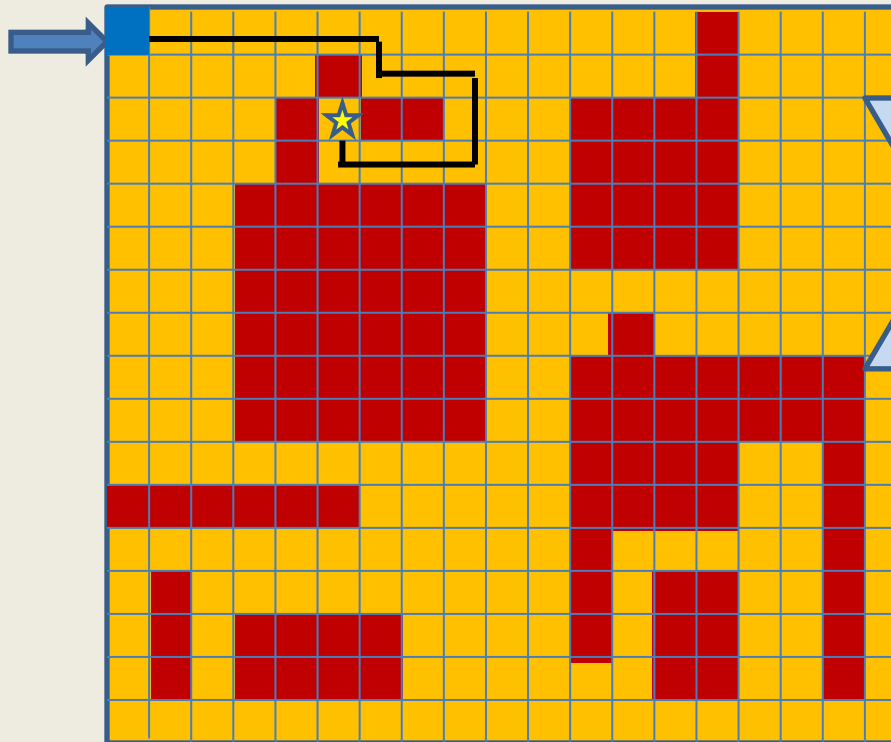


# Step 1:

Realizing  
the **nontriviality** of the problem

# Shortest route in a grid

## nontriviality of the problem



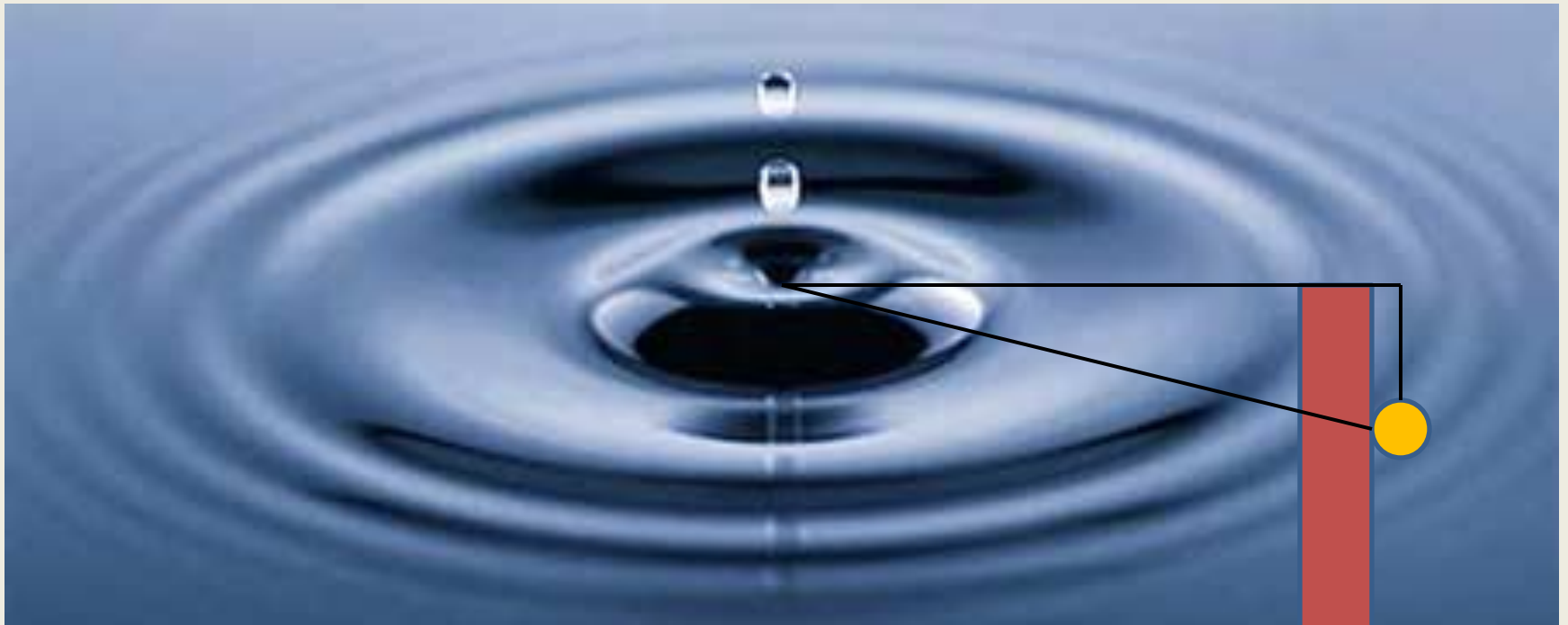
Don't proceed to the next slide until you are convinced about the non-triviality and beauty of this problem 😊

**Definition:** Distance of a cell  $c$  from another cell  $c'$  is the length (number of steps) of the shortest route between  $c$  and  $c'$ .

**We shall design algorithm for computing distance of each cell from the start-cell.**

As an exercise, you should extend it to a data structure for retrieving shortest route.

# Get **inspiration** from nature

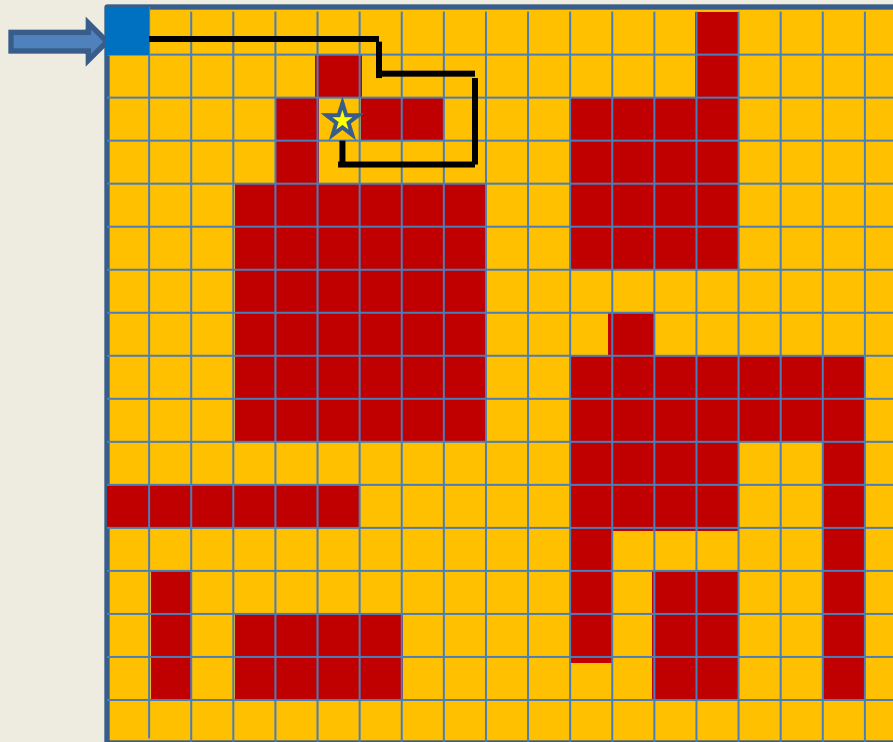


**The ripples travels along the shortest route ?**

# Shortest route in a grid

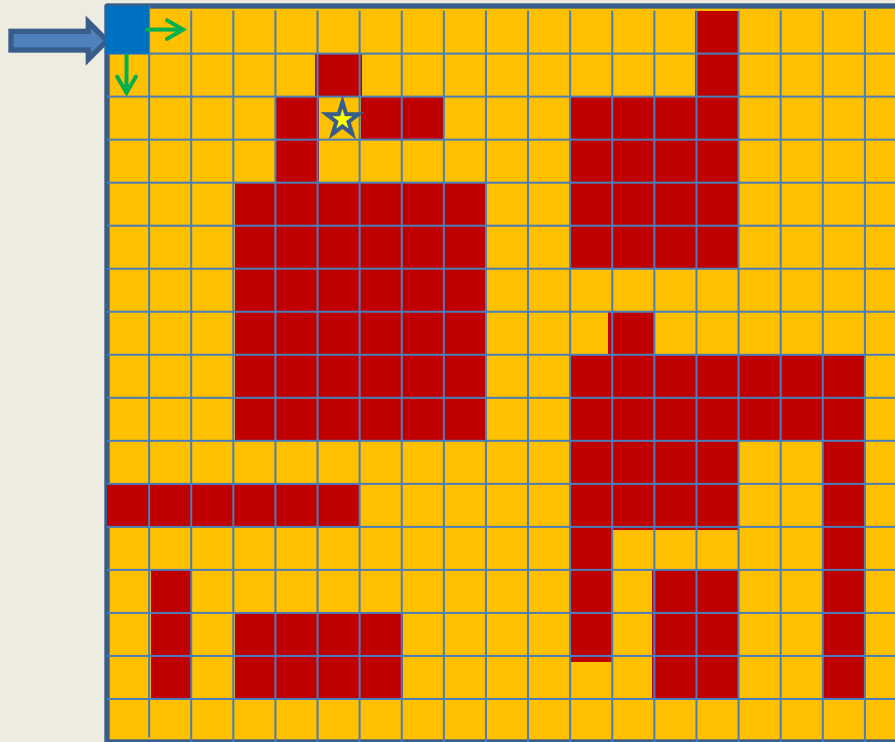
nontriviality of the problem

## How to find the shortest route to ★ in the grid ?



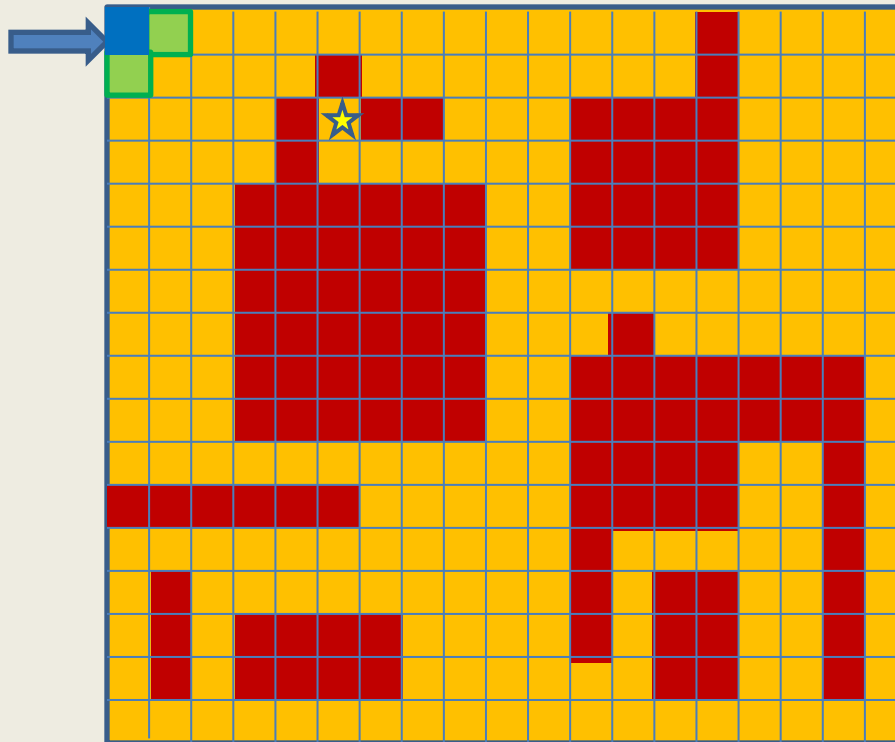
Create a ripple at the start cell and trace the path it takes to ★

## propagation of a ripple from the start cell

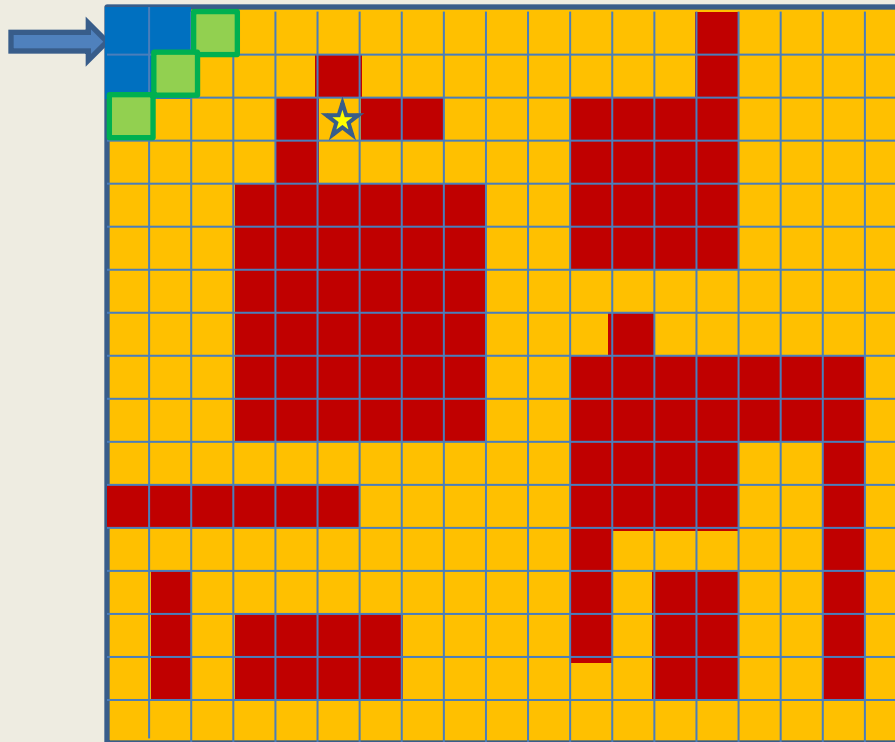




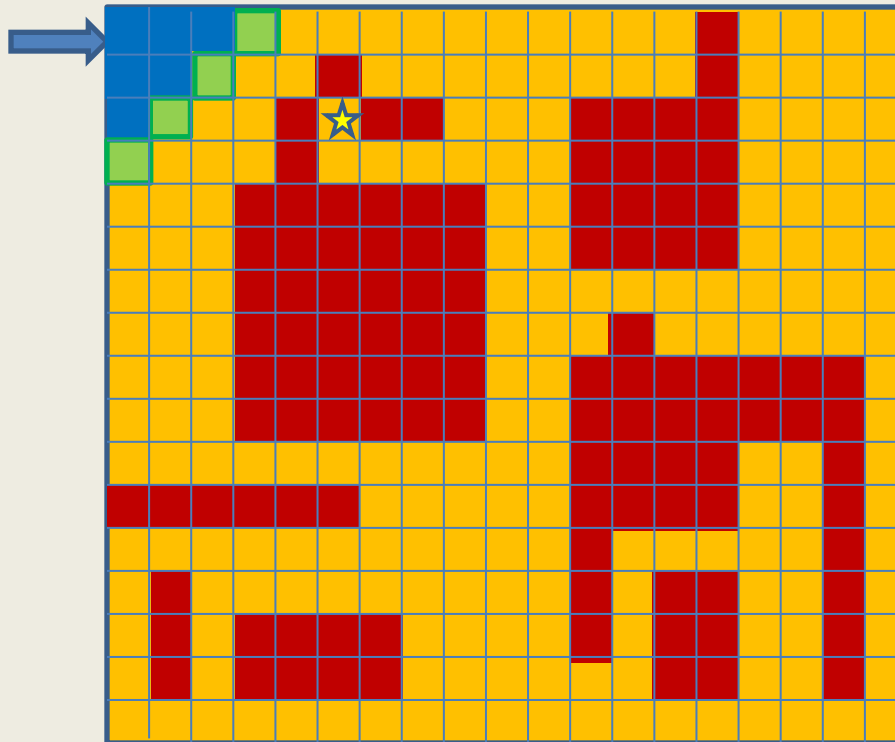
ripple **reaches** cells at **distance 1** in **step 1**



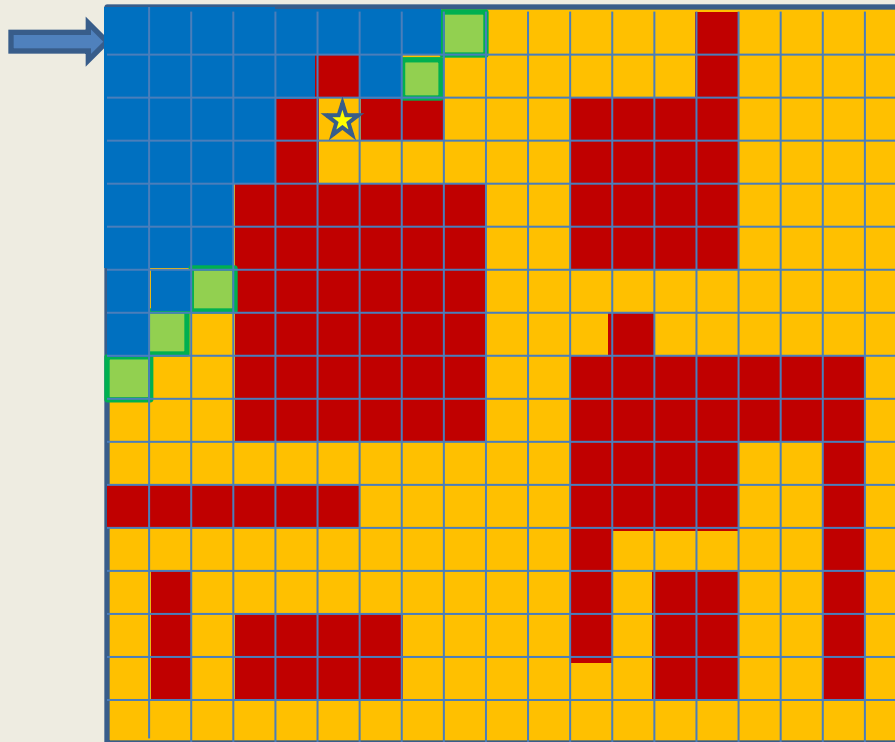
ripple **reaches** cells at **distance 2** in **step 2**



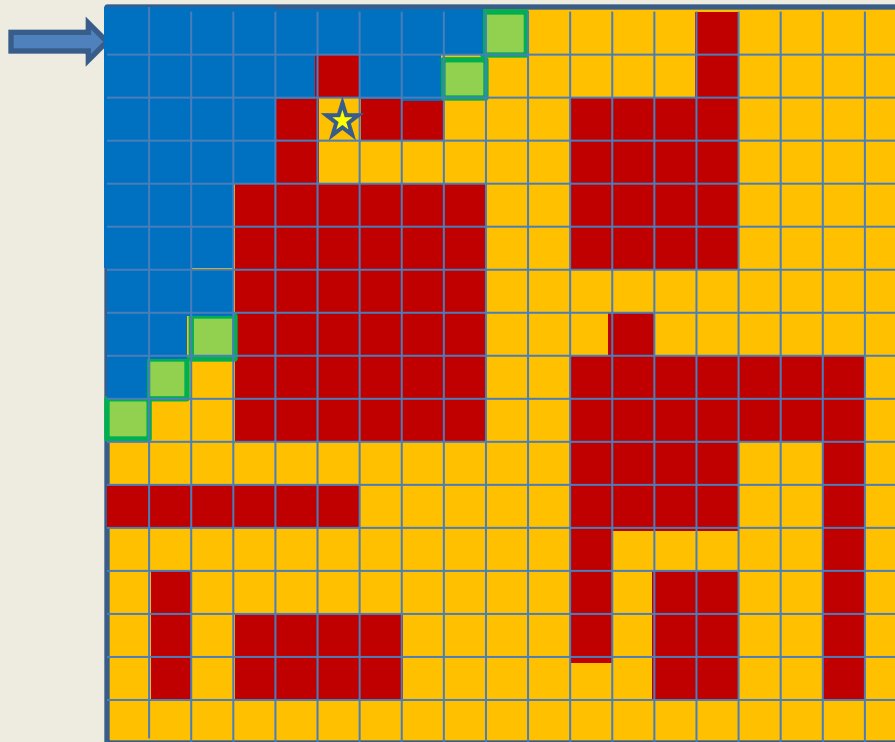
ripple **reaches** cells at **distance 3** in **step 3**



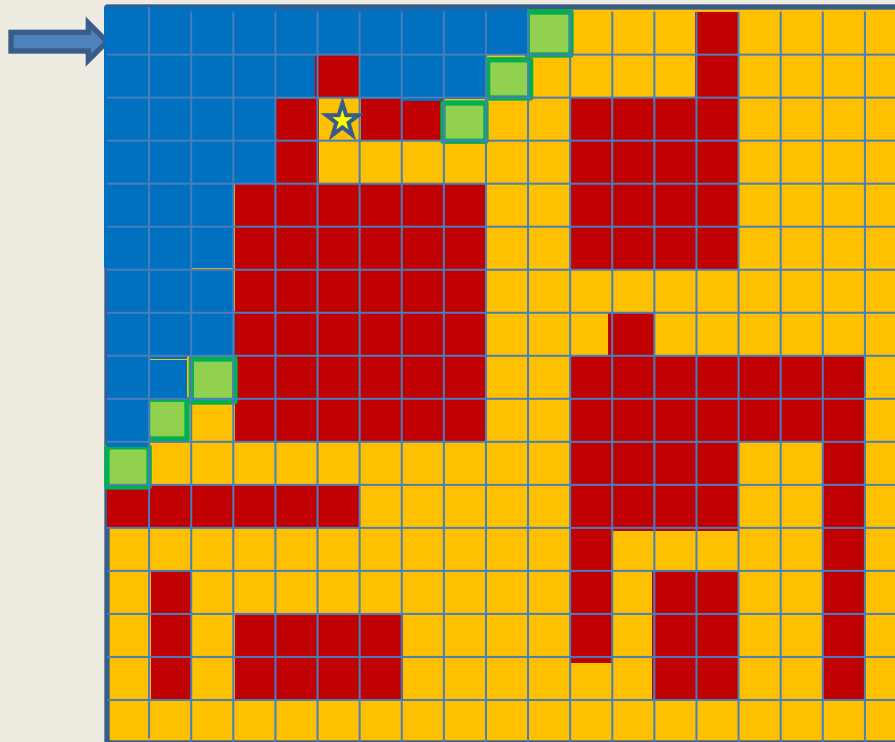
ripple **reaches** cells at **distance 8** in **step 8**



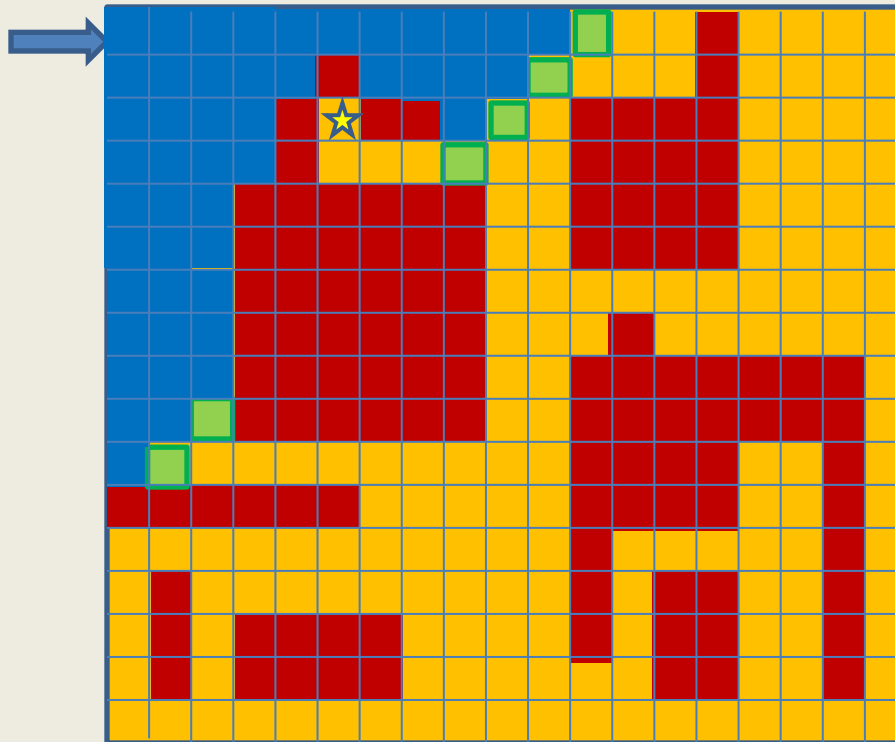
ripple **reaches** cells at **distance 9** in **step 9**



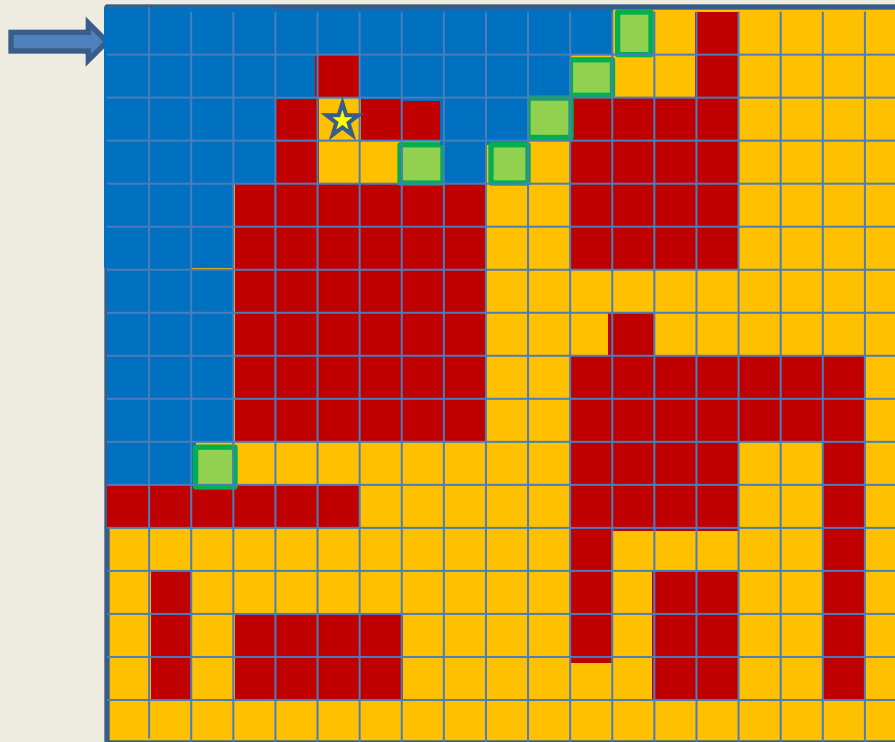
ripple reaches cells at distance 10 in step 10



ripple reaches cells at distance 11 in step 11

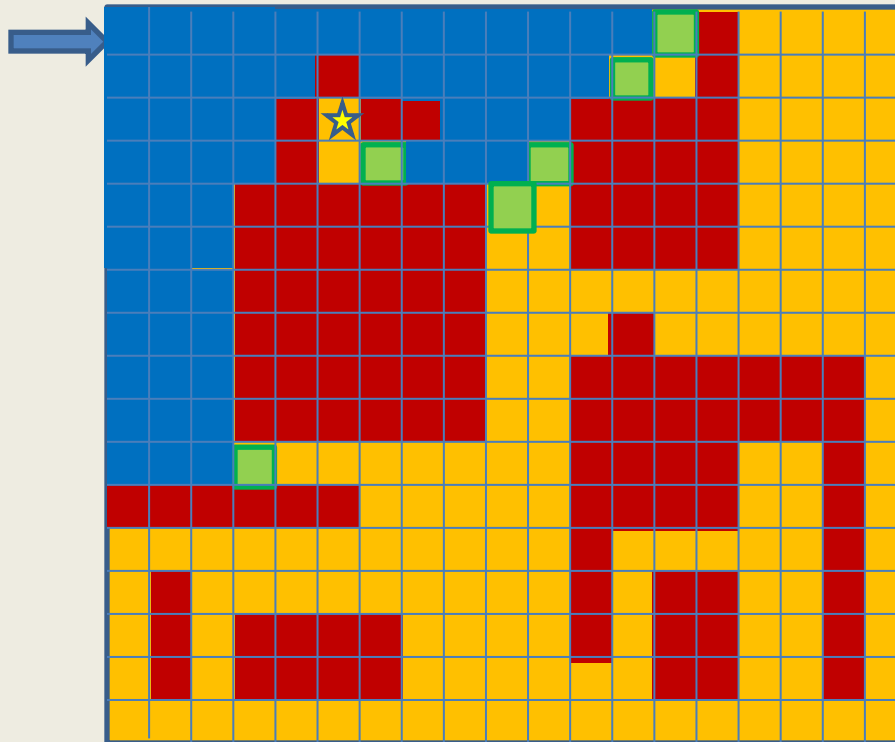


**ripple reaches cells at distance 12 in step 12**

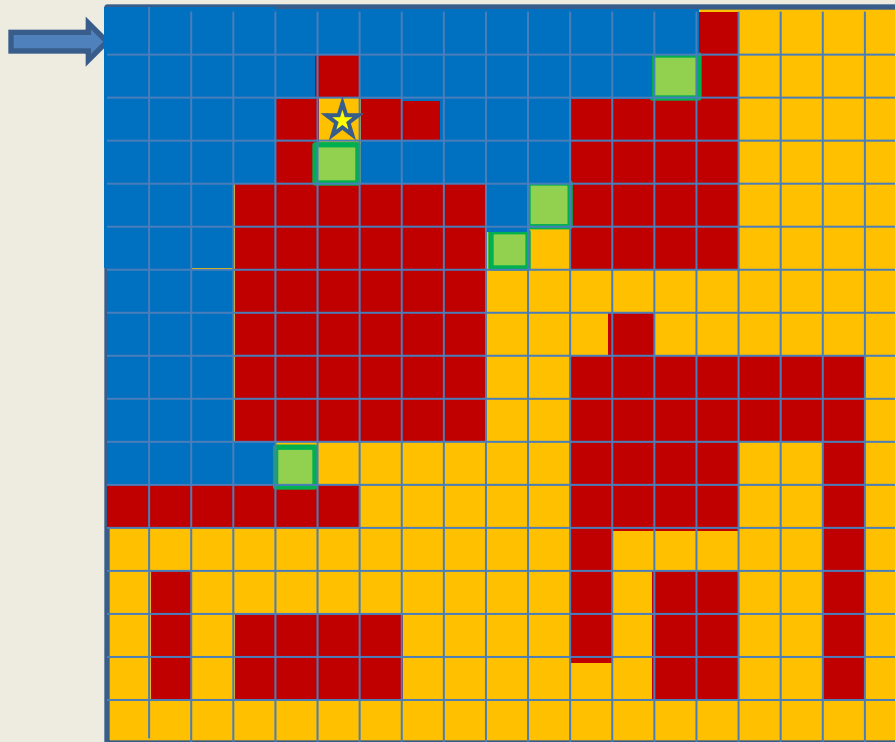




ripple reaches cells at distance 13 in step 13

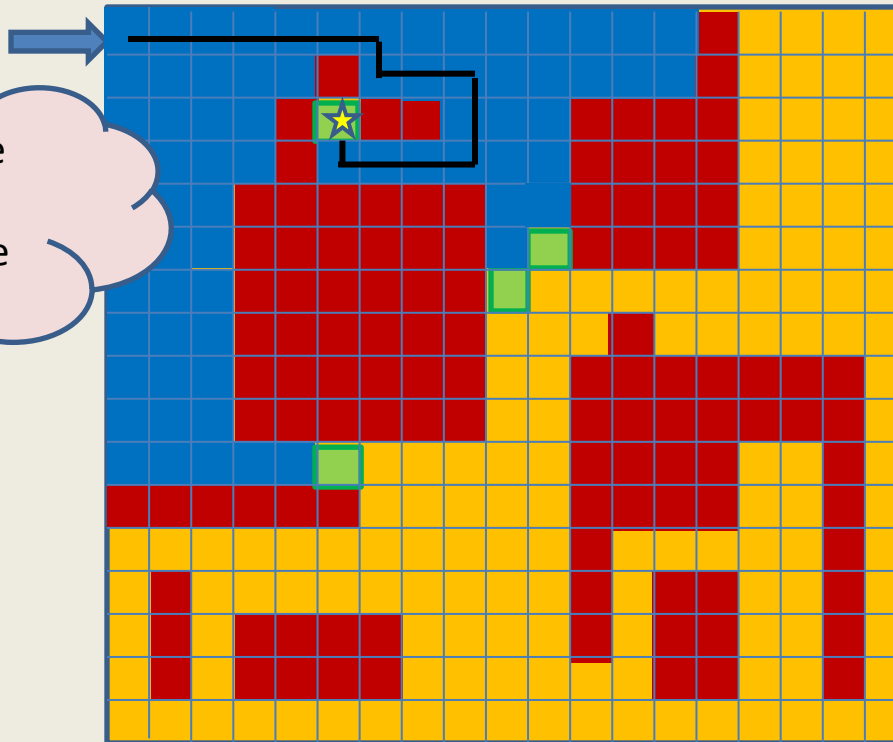


ripple reaches cells at distance 14 in step 14



ripple reaches cells at distance 15 in step 15

Did you get some insight into the problem from the animation ?



The route taken by ripple is indeed the shortest.

Think for a few more minutes with a free mind 😊.

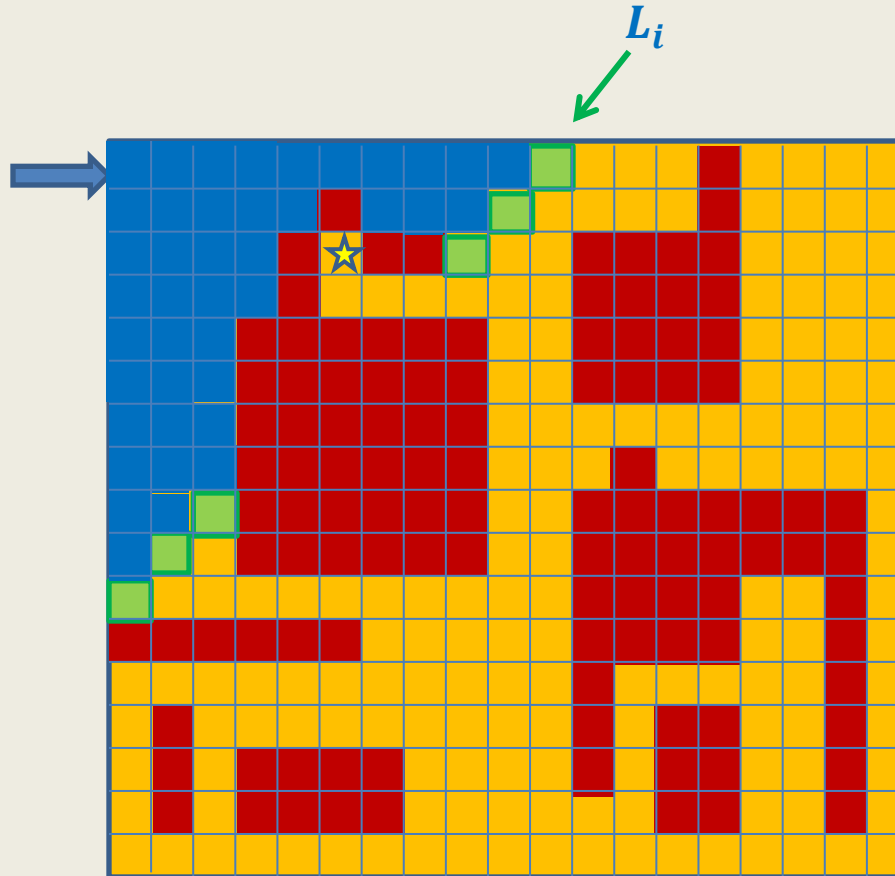
# **Step 2:**

## **Designing algorithm for distances in grid**

**(using an insight into propagation of ripple)**

**A snapshot of ripple after  $i$  steps**

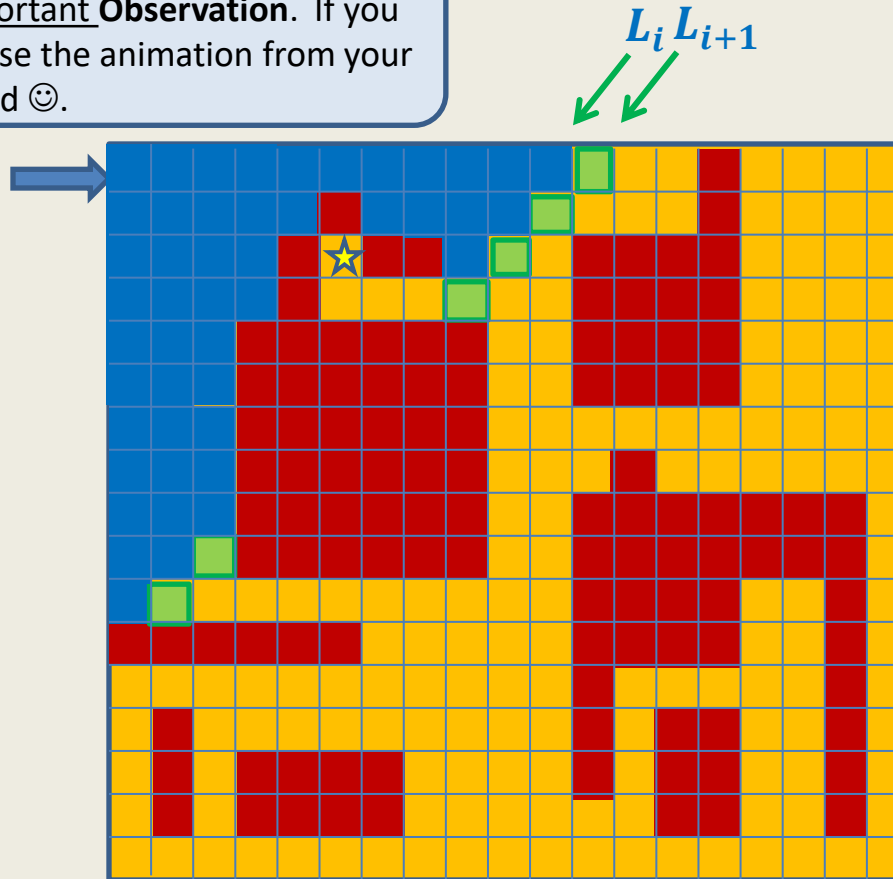
## A snapshot of ripple after $i$ steps



$L_i$  : the cells of the grid at distance  $i$  from the starting cell.

## A snapshot of the ripple after $i + 1$ steps

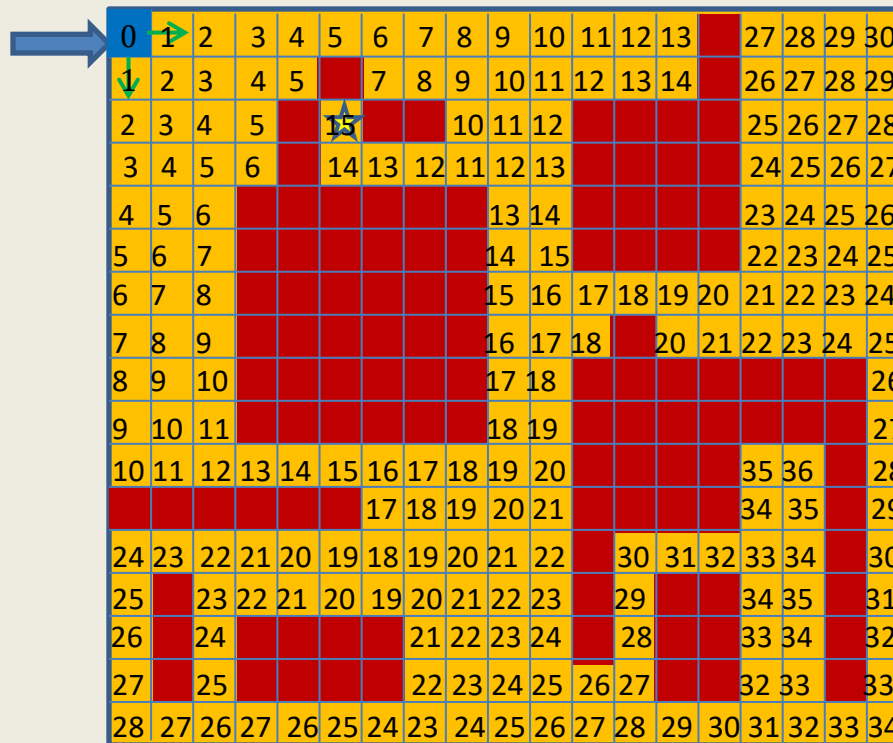
All the hardwork on the animation was done just to make you realize this important Observation. If you have got it, feel free to erase the animation from your mind 😊.



**Observation:** Each cell of  $L_{i+1}$  is a neighbor of a cell in  $L_i$ .

## Distance from the start cell

It is worth spending some time on this matrix.  
Does the matrix give some idea to answer the question ?



0	1	2	3	4	5	6	7	8	9	10	11	12	13		27	28	29	30
	2	3	4	5		7	8	9	10	11	12	13	14		26	27	28	29
2	3	4	5		15			10	11	12					25	26	27	28
3	4	5	6		14	13	12	11	12	13					24	25	26	27
4	5	6							13	14					23	24	25	26
5	6	7							14	15					22	23	24	25
6	7	8							15	16	17	18	19	20	21	22	23	24
7	8	9							16	17	18		20	21	22	23	24	25
8	9	10							17	18								26
9	10	11							18	19								27
10	11	12	13	14	15	16	17	18	19	20					35	36		28
						17	18	19	20	21					34	35		29
24	23	22	21	20	19	18	19	20	21	22		30	31	32	33	34		30
25		23	22	21	20	19	20	21	22	23		29			34	35		31
26		24					21	22	23	24		28			33	34		32
27		25					22	23	24	25	26	27			32	33		33
28	27	26	27	26	25	24	23	24	25	26	27	28	29	30	31	32	33	34

How can we  
generate  $L_{i+1}$   
from  $L_i$  ?

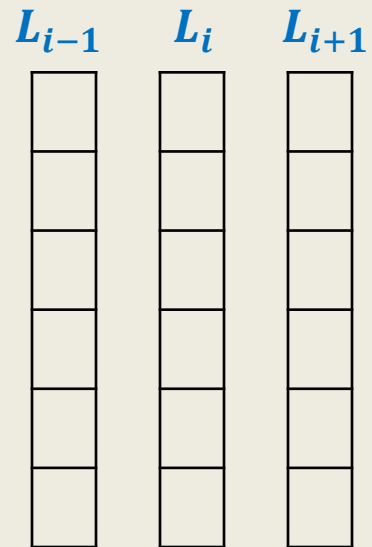
**Observation:** Each cell of  $L_{i+1}$  is a neighbor of a cell in  $L_i$ .

But every neighbor of  $L_i$  may be a cell of  $L_{i-1}$  or  $L_{i+1}$ .



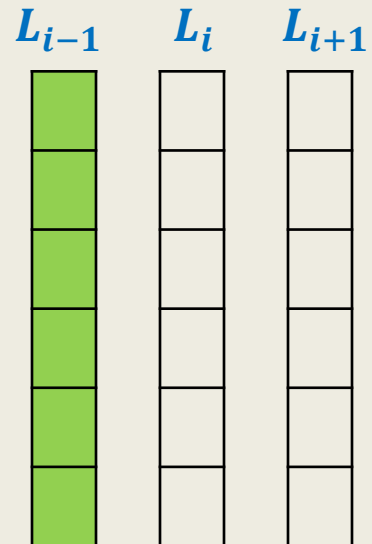
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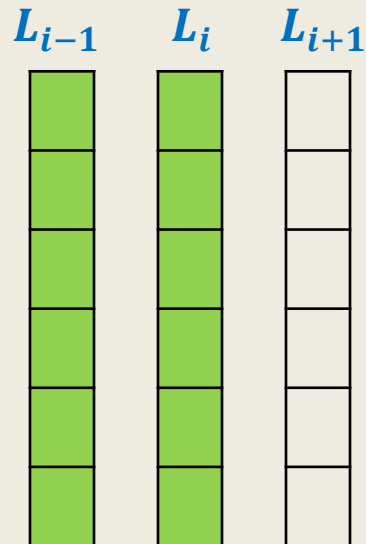
# How can we generate $L_{i+1}$ from $L_i$ ?

Suppose all cells of  $L_{i-1}$  get visited first.



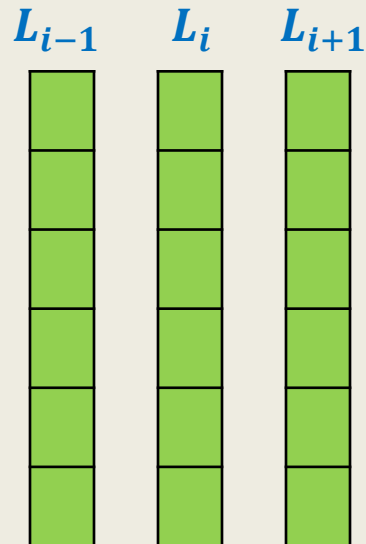
# How can we generate $L_{i+1}$ from $L_i$ ?

Suppose all cells of  $L_{i-1}$  get visited first.  
Then all cells of  $L_i$  are visited, and



# How can we generate $L_{i+1}$ from $L_i$ ?

Suppose all cells of  $L_{i-1}$  get visited first.  
Then all cells of  $L_i$  are visited, and  
then all cells of  $L_{i+1}$  are visited.



So by the time all cells of  $L_i$  are visited, if a cell neighboring to a cell of  $L_i$  is unvisited, it must be a cell of  $L_{i+1}$ .



# How can we generate $L_{i+1}$ from $L_i$ ?

So the algorithm should be:

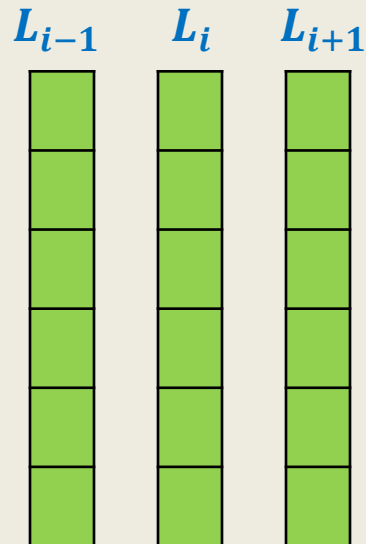
Initialize the distance of all cells except start cell as  $\infty$

First compute  $L_1$ .

Then using  $L_1$  compute  $L_2$

Then using  $L_2$  compute  $L_3$

...



# Algorithm to compute $L_{i+1}$ if we know $L_i$

Compute-next-layer( $G, L_i$ )

{

  CreateEmptyList( $L_{i+1}$ );

  For each cell  $c$  in  $L_i$

    For each neighbor  $b$  of  $c$  which is not an obstacle

      { if ( $\text{Distance}[b] = \infty$ )

        { Insert( $b, L_{i+1}$ );

$\text{Distance}[b] \leftarrow i + 1$  ;

        }

    }

  return  $L_{i+1}$ ;

}

# The first (not so elegant) algorithm

(to compute distance to all cells in the grid)

Distance-to-all-cells( $G, c_0$ )

{  $L_0 \leftarrow \{c_0\};$

For( $i = 0$  to  $??$ )

$L_{i+1} \leftarrow \text{Compute-next-layer}(G, L_i);$

}

It can be as high as  
 $O(n^2)$

The algorithm is not elegant because of

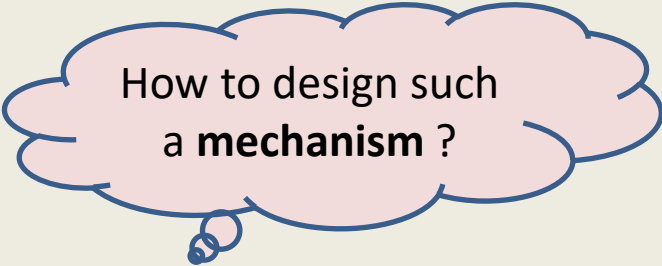
- So many temporary lists that get created.



# Towards an **elegant** algorithm ...

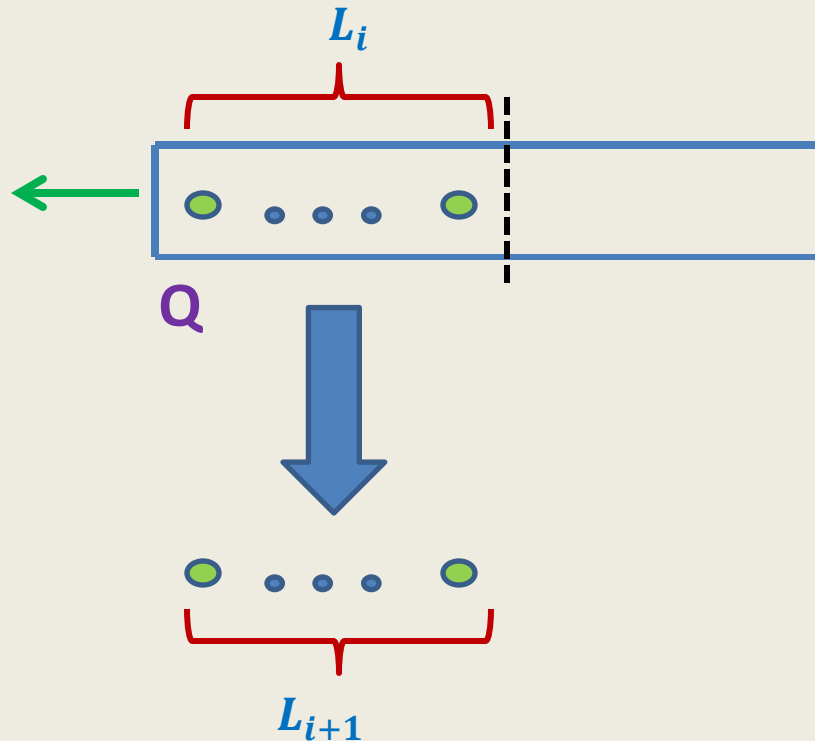
## Key points we observed:

- We can compute cells at distance  $i + 1$  if we know all cells up to distance  $i$ .
- Therefore, we need a mechanism to enumerate the cells in **non-decreasing** order of distances from the start cell.



How to design such  
a **mechanism** ?

# Keep a queue $Q$



Spend some time to see how seamlessly the queue ensured the requirement of visiting cells of the grid in non-decreasing order of distance.

# An elegant algorithm

(to compute distance to all cells in the grid)

Distance-to-all-cells( $G, c_0$ )

CreateEmptyQueue( $Q$ );

Distance( $c_0$ )  $\leftarrow 0$ ;

Enqueue( $c_0, Q$ );

While( Not IsEmptyQueue( $Q$ ) )

{  
   $c \leftarrow$  Dequeue( $Q$ );

  For each neighbor  $b$  of  $c$  which is not an obstacle

  {   if (Distance( $b$ ) =  $\infty$ )

    {   Distance( $b$ )  $\leftarrow$  Distance( $c$ ) + 1 ;

    Enqueue( $b, Q$ ); ;

  }

}

}

# Proof of correctness of algorithm

**Question:** What is to be proved ?

**Answer:** At the end of the algorithm,

**Distance**[*c*]= the distance of cell *c* from the starting cell in the grid.

**Question:** How to prove ?

**Answer:** By the principle of mathematical induction on

**the distance** from the starting cell.

**Inductive assertion:**

**P(*i*):**

The algorithm correctly computes distance to all cells at distance *i* from the starting cell.

As an exercise, try to prove **P(*i*)** by induction on *i*.