Data Structures and Algorithms (CS210A)



Height balanced BST

Red-black trees

Terminologies

Full binary tree:

A binary tree where every internal node has exactly two children.



Terminologies

Complete binary tree:

A full binary tree where every leaf node is at the same level.





Binary Search Tree



Definition: A Binary Tree **T** storing values is said to be Binary Search Tree if for each node **v** in T

- If left(v) <> NULL, then value(v) > value of every node in subtree(left(v)).
- If right(v)<>NULL, then value(v) < value of every node in subtree(right(v)).



 \rightarrow

A fact we noticed in our previous discussion on BSTs (Lecture 9)

Time complexity of Search(T,x) and Insert(T,x) in a Binary Search Tree T = O(Height(T))

Height(*T*):

The maximum number of nodes on any path from root to a leaf node.

Searching and inserting in a perfectly balanced BST



Searching and inserting in a skewed BST on *n* nodes



Nearly balanced Binary Search Tree

Terminology:

size of a binary tree is the number of nodes present in it.

Definition: A binary search tree **T** is said to be <u>nearly balanced</u> at node **v**, if size(left(v)) $\leq \frac{3}{4}$ size(v) and size(right(v)) $\leq \frac{3}{4}$ size(v)

Definition: A binary search tree T is said to be nearly balanced if it is <u>nearly balanced</u> at each node.

Nearly balanced Binary Search Tree

- **Search(T,x)** operation is the same.
- Modify Insert(T,x) operation as follows:
 - Carry out normal insert and update the size fields of nodes traversed.
 - If BST T is ceases to be nearly imbalanced at any node v, transform subtree(v) into perfectly balanced BST.
- \rightarrow **O**(log *n*) time for search
- → $O(n \log n)$ time for *n* insertions –

Disadvantages:

- How to handle **deletions** ?
- Some insertions may take O(n) time ⊗

This fact will be proved soon in the next to the next class.

Can we achieve O(log n) time for search/insert/delete ?

- AVL Trees [1962]
- Red Black Trees [1978]

Rotation around a node

An important tool for balancing trees

Each height balanced **BST** employs this tool which is derived from the **flexibility** which is <u>hidden</u> in the structure of a **BST**. This flexibility (**pointer manipulation**) was inherited from linked list ⁽²⁾.

Rotation around a node



Note that the tree **T** continues to remain a BST even after rotation around any node.

Red Black Tree A height balanced BST

Red Black Tree

Red-Black tree is a binary search tree satisfying the following properties:

- Each node is colored red or black.
- Each leaf is colored **black** and so is the root.
- Every red node will have both its children black.
- No. of <u>black nodes</u> on a path from root to each leaf node is same.
 black height

A binary search tree



A binary search tree



Why is a red black tree height balanced ?

T : a red black treeh : black height of T.



Homework: Ponder over the above hint to prove that **T** has $\geq 2^{h} - 1$ elements¹⁸

Insertion in a Red Black tree

All it involves is

- playing with colors 😳
- and rotations 🙂















Insertion in a red-black tree summary till now ...

Let *p* be the newly inserted node. Assign **red** color to *p*.

Case 1: parent(p) is black

nothing needs to be done.

Case 2: parent(p) is red and uncle(p) is red,

Swap colors of *parent* (and *uncle*) with *grandparent*(*p*).

This balances the color at p but may lead to <u>imbalance</u> of color at grandparent of p. So $p \leftarrow grandparent(p)$, and proceed upwards similarly. If in this manner p becomes **root**, then we color it **black**.

Case 3: *parent*(*p*) is **red** and *uncle*(*p*) is **black**.

This is a nontrivial case. So we need some more tools

Handling case 3

Description of Case 3

- *p* is a **red** colored node.
- parent(p) is also red.
- uncle(p) is black.

Without loss of generality assume: *parent(p)* is *left child* of grandparent(p).

(The case when *parent(p)* is *right child* of *grandparent(p)* is handled similarly.)

two cases arise depending upon whether p is left/right child of its parent



two cases arise depending upon whether p is left/right child of its parent



We need to handle only case 3.1











Theorem:

We can maintain **red-black** trees under insertion of nodes in $O(\log n)$ time per <u>insert/search</u> operation where n is the number of the nodes in the tree.

I hope you enjoyed the real fun in handling insertion in a **red black** tree.

The following are the natural questions to ask.

- Why we are handling insertions in "this *particular* way"?
- Are there *alternative and simpler* ways to handle insertions ?

You are encouraged to explore the answer to both these questions. You are welcome to discuss them with me. • Please solve the problem on the following slide.

How to insert 4?

How do will we handle deletion ?

This is going to be a bit more complex.

So please try on your own first before coming to the next class.

It will still involve playing with colors and rotations \odot

